



Universidade Federal  
do Rio de Janeiro

Escola Politécnica

DATA

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GRAUS:

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Aluno: PROVA PARCIAL #2 — GABRIELITO

Disciplina: CONTROLE LINEAR II-A

Turma: EEL760  
2009/2

Professor: JOSÉ GABRIEL R.C. GONES

QUESTÃO #1:

$$a) \frac{D(s)}{s} = \frac{s+1}{s(s+2)} = \frac{1/2}{s} + \frac{1/2}{s+2} \quad \therefore u(t) = \frac{1}{2} (1 + e^{-2t}) u(t)$$

$$b) u(k) = \frac{1}{2} (1 + e^{-2Tk}) u(k)$$

$$U(z) = \frac{1}{2} \left( \frac{z}{z-1} + \frac{z}{z-e^{-2T}} \right) \Rightarrow D(z) = \frac{1}{2} \left( 1 + \frac{z-1}{z-e^{-2T}} \right) = \frac{z - \left( \frac{1+e^{-2T}}{2} \right)}{z-e^{-2T}}$$

$$c) U(z) = \frac{z}{z-1} \cdot \frac{z-a}{z-b} \Rightarrow \frac{U(z)}{z} = \frac{1-a}{z-1} + \frac{b-a}{z-b} = \frac{1/2}{z-1} + \frac{1/2}{z-e^{-2T}}$$

$$\frac{1 - \left( \frac{1+e^{-2T}}{2} \right)}{1-e^{-2T}} = \frac{1}{2} \quad \quad \quad \frac{e^{-2T} - \left( \frac{1+e^{-2T}}{2} \right)}{e^{-2T}-1} = \frac{1}{2}$$

$$u(k) = \left( \frac{1}{2} \right) (1 + e^{-2Tk}) u(k) \quad (\text{JÁ SABÍAMOS ISTO, DO ITEM (b)})$$

d) BIUNEDR:

$$D(z) = \frac{\frac{2}{T} \left( \frac{z-1}{z+1} \right) + 1}{\frac{2}{T} \left( \frac{z-1}{z+1} \right) + 2} = \frac{2z-2+Tz+T}{2z-2+2Tz+2T} = \frac{(T+2)z+T-2}{(2T+2)z+2T-2}$$

$$U(z) = \frac{z}{z-1} \cdot \frac{\left( \frac{T+2}{2T+2} \right) z + \frac{T-2}{2T+2}}{z + \left( \frac{2T-2}{2T+2} \right)} = \frac{z}{z-1} \cdot \frac{az+b}{z+c}$$

$$\frac{U(z)}{z} = \frac{a+b}{z-1} + \frac{ac-b}{z+c}$$

$$a+b = \frac{T}{T+1} \quad ; \quad c+1 = \frac{2T}{T+1} \quad ; \quad ac-b = \frac{(T+2)(T-1)z - (T-2)(T+1)z}{4(T+1)^2} = \frac{T}{4(T+1)^2}$$

$$\frac{ac-b}{c+1} = \frac{1}{2(T+1)} \quad \leftarrow \quad ac-b = \frac{2(T^2+T-z-z^2+T+z)}{4(T+1)^2} = \frac{T}{4(T+1)^2}$$

$$u(k) = \left( \frac{1}{2} + \frac{1}{2(T+1)} \left( \frac{z-2T}{z+2T} \right)^k \right) u(k)$$

QUESTÃO #2:

a)  $F = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}; G = \begin{bmatrix} 1 \\ 0 \end{bmatrix}; H = [0 \ 1];$

$$e^{FT} = \mathcal{L}^{-1} \left[ (sI - F)^{-1} \right]_{t=T} = \mathcal{L}^{-1} \left[ \begin{bmatrix} s & 0 \\ -1 & s \end{bmatrix}^{-1} \right]_{t=T} = \mathcal{L}^{-1} \left[ \begin{bmatrix} \frac{1}{s} & 0 \\ \frac{1}{s^2} & \frac{1}{s} \end{bmatrix} \right]_{t=T}$$

$$e^{FT} = \begin{bmatrix} 1 & 0 \\ T & 1 \end{bmatrix}; \Gamma = \begin{bmatrix} T & 1 \\ 0 & 1 \end{bmatrix}; \Delta G = \begin{bmatrix} T \\ T^2/2 \end{bmatrix}$$

(OBS.:  $G(z) = [0 \ 1] \begin{bmatrix} z^{-1} & 0 \\ -Tz^{-1} & z^{-1} \end{bmatrix}^{-1} \begin{bmatrix} T \\ T^2/2 \end{bmatrix} = [0 \ 1] \begin{bmatrix} z^{-1} & 0 \\ T & z^{-1} \end{bmatrix} \begin{bmatrix} T \\ T^2/2 \end{bmatrix} = \frac{T^2(z+1)}{2(z-1)^2}$ )

b)  $\alpha_c(z) = z^2 - (e^{s_1 T} + e^{s_1^* T})z + e^{T \text{Re}(s_1 + s_1^*)} = z^2 + (-2\text{Re}(e^{s_1 T}))z + e^{2T \text{Re}(s_1)}$

$$\begin{bmatrix} 1 & 0 \\ T & 1 \end{bmatrix} - \begin{bmatrix} T \\ T^2/2 \end{bmatrix} \begin{bmatrix} k_1 & k_2 \end{bmatrix} = \begin{bmatrix} 1 - Tk_1 & -Tk_2 \\ T - \frac{T^2}{2}k_1 & 1 - \frac{T^2}{2}k_2 \end{bmatrix}$$

$$\begin{vmatrix} z + Tk_1 - 1 & Tk_2 \\ \frac{T^2}{2}k_1 - T & z + \frac{T^2}{2}k_2 - 1 \end{vmatrix} = z^2 + \left( Tk_1 + \frac{T^2}{2}k_2 - 2 \right)z - Tk_1 + \frac{T^2}{2}k_2 + 1$$

$$Tk_1 + \frac{T^2}{2}k_2 = 2 - 2\text{Re}(e^{s_1 T}) \Rightarrow k_1 = \frac{3 - 2\text{Re}(e^{s_1 T}) - e^{2T \text{Re}(s_1)}}{T}$$

$$-Tk_1 + \frac{T^2}{2}k_2 = -1 + e^{2T \text{Re}(s_1)} \Rightarrow k_2 = \frac{1 + e^{2T \text{Re}(s_1)} - 2\text{Re}(e^{s_1 T})}{T}$$

c)  $\begin{bmatrix} 1 & 0 \\ T & 1 \end{bmatrix} - \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} [0 \ 1] = \begin{bmatrix} 1 - a_1 & -a_1 \\ T & 1 - a_2 \end{bmatrix}$

$$\begin{vmatrix} z - 1 & a_1 \\ -T & z + a_2 - 1 \end{vmatrix} = z^2 + (a_2 - 2)z + a_1 T - a_2 + 1$$

$$a_1 T + a_2 = -1 + e^{2T \text{Re}(s_2)}$$

$$a_2 = \frac{2 - 2\text{Re}(e^{s_2 T})}{T} \Rightarrow a_1 = \frac{-3 + e^{2T \text{Re}(s_2)} + 2\text{Re}(e^{s_2 T})}{T}$$

d)  $f_p = \frac{\pi}{\omega} = \frac{3.14}{10} = 0.314 \Rightarrow \text{EM } 32 \text{ AMOSTRAS. } T = 0.01$

QUESTÃO #3:

a)  $\phi - L\phi = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} - \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} [1 \ 1] = \begin{bmatrix} 1 - a_1 & -a_1 \\ 1 - a_2 & 1 - a_2 \end{bmatrix}$

$$(zI - \phi + L\psi) = \begin{vmatrix} z+q-1 & q \\ q-1 & z+q-1 \end{vmatrix} = z^2 + (q+q-2)z + (-q-q+1+q) \quad (2)$$

$$L_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$q+q=2 \Rightarrow q=1$$

$$-q-1+q=0 \Rightarrow q=1$$

$$b) \phi - L\psi - \Gamma K + L\psi\Gamma K = \begin{bmatrix} -2 & -2 \\ 0 & 0 \end{bmatrix}$$

$$\hat{x}(k+1) = \begin{bmatrix} -2 & -2 \\ 0 & 0 \end{bmatrix} \hat{x}(k) + \begin{bmatrix} 1 \\ 1 \end{bmatrix} y(k+1)$$

$$u(k) = -[2 \ 1] \hat{x}(k)$$

$$D(z) = -[2 \ 1] \begin{bmatrix} z+2 & 2 \\ 0 & z \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix} z = -[2 \ 1] \begin{bmatrix} z & -2 \\ 0 & z+2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} z$$

$$D(z) = \frac{-[2z \ z-2] \begin{bmatrix} 1 \\ 1 \end{bmatrix} z}{z^2+2z} \Rightarrow \boxed{D(z) = \frac{-3z+2}{z+2}}$$

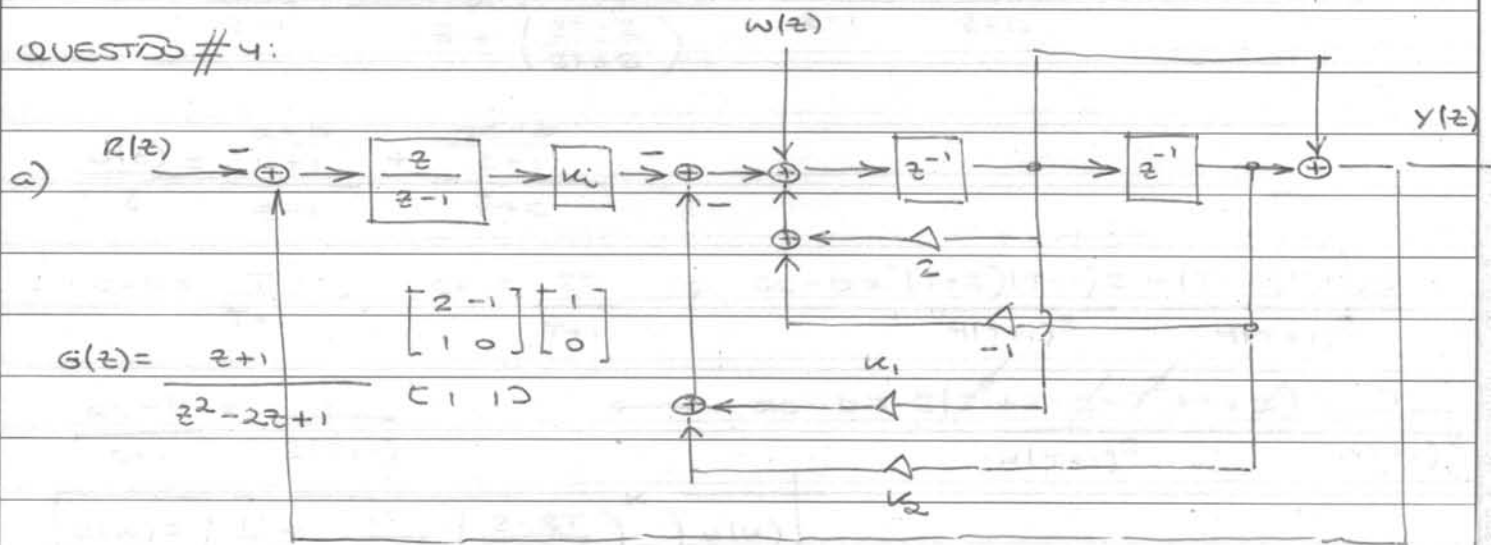
$$c) G(z) = [0 \ 1] \begin{bmatrix} z-1 & 0 \\ -1 & z-1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = [0 \ 1] \begin{bmatrix} z-1 & 0 \\ 1 & z-1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{(z-1)^2}$$

$$\frac{G}{1-GD} = \frac{1}{(z-1)^2} = \frac{z+2}{z^3} \quad \text{GANHO DC} = 2.$$

$$\frac{1}{z^2 - 2z + 1} \Rightarrow \begin{array}{c|ccc} 1 & -2 & 1 & \\ \hline 2 & 1 & 1 & \\ & 2 & 1 & \\ & & 2 & 1 & \end{array} \begin{array}{l} 1 \\ 0 \\ -2 \\ 2 \end{array}$$

$$d) \bar{n} = 1/2$$

QUESTÃO #4:



$$G(z) = \frac{z+1}{z^2-2z+1}$$

$$\begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

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$$b) \begin{bmatrix} 1 & 1 & 1 \\ 0 & z-1 & -1 \\ 0 & 1 & 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} [k_1 \ k_2 \ k_3] = \begin{bmatrix} 1 & 1 & 1 \\ -k_1 & z-k_1 & -1-k_2 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\begin{vmatrix} z-1 & -1 & -1 \\ k_1 & z+k_1-2 & k_2+1 \\ 0 & -1 & z \end{vmatrix} = z^3 + z^2(k_1-2-1) + (2-k_1)z + k_1 + (k_2+1)z + (-k_2-1) + k_1z$$

$$= z^3 + (k_1-3)z^2 + (3-k_1+k_2+k_1)z + k_1 - k_2 - 1$$

$$\boxed{k_1=3} \quad k_2+k_1=0 \Rightarrow \boxed{k_2=-1/2} \quad \boxed{k_1=+1/2}$$

$$k_2-k_1=-1$$

$$c) \frac{Y(z)}{R(z)} = C \begin{bmatrix} z-1 & -1 & -1 \\ 0.5 & z+1 & 0.5 \\ 0 & -1 & z \end{bmatrix}^{-1} \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} = \frac{(-1)}{z^3} \left[ \begin{vmatrix} 0.5 & 0.5 \\ 0 & z \end{vmatrix} (-1) + \begin{vmatrix} 0.5 & z+1 \\ 0 & -1 \end{vmatrix} \right]$$

$$\frac{Y(z)}{R(z)} = \frac{(-1)(-0.5z - 0.5)}{z^3} = \frac{0.5(z+1)}{z^3} \quad \lim_{z \rightarrow 1} \frac{Y(z)}{R(z)} = \boxed{1}$$

$$\frac{Y(z)}{W(z)} = C \begin{bmatrix} z-1 & -1 & -1 \\ 0.5 & z+1 & 0.5 \\ 0 & -1 & z \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \frac{1}{z^3} \left[ \begin{vmatrix} z-1 & -1 \\ 0 & z \end{vmatrix} + (-1) \begin{vmatrix} z-1 & -1 \\ 0 & -1 \end{vmatrix} \right]$$

$$\frac{Y(z)}{W(z)} = \frac{z^2-1}{z^3} \quad \lim_{z \rightarrow 1} \frac{Y(z)}{W(z)} = \boxed{0}$$