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Aluno: GABARITO DA PROVA PARCIAL #2

Disciplina: CONTROLE LINEAR II-A

Turma: EEL760

Professor: JOSÉ GABRIEL

QUESTÃO #1:

a)  $U(s) = \frac{1}{s(s+1)} = \frac{1}{s} - \frac{1}{s+1} \rightarrow u(t) = (1 - e^{-t})u(t)$

b)  $U(z) = \frac{z(1-e^{-T})}{(z-1)(z-e^{-T})}$ ;  $\frac{U(z)}{z} = \frac{1}{z-1} + \frac{(-1)}{z-e^{-T}}$

$u(k) = (1 - e^{-Tk})u(k)$

MÉTODOS: MAPEAMENTO PÓLOS E ZEROS; EQUIVALÊNCIA NA RESPOSTA DO DEGRU; DISCRETIZAÇÃO NO ESPAÇO DE ESTADOS

c)  $U(z) = \left( \frac{T}{T+2} \right) \frac{z(z+1)}{(z-1)(z-a)}$ ;  $a = -\frac{T-2}{T+2}$

$\frac{U(z)}{z} = \frac{T}{T+2} \left( \frac{z+1}{(z-1)(z-a)} \right) = \frac{T}{T+2} \left( \frac{2}{z-1} + \frac{a+1}{z-a} \right)$

$\frac{2}{1-a} = \frac{T+2}{T} = \frac{a+1}{a-1} = \frac{-2}{-T}$

$U(z) = \frac{1}{z} + \left( \frac{-2}{T+2} \right) \frac{1}{z-a} \rightarrow u(k) = \left( 1 - \frac{2}{T+2} \left( \frac{-1+2}{T+2} \right)^k \right) u(k)$

MÉTODOS: BILINEAR

d)  $U(z) = \frac{zT}{(z-1)(z+T-1)}$ ;  $\frac{U(z)}{z} = T \left( \frac{-1/T}{z-1} + \frac{(1/T)}{z+T-1} \right)$

$U(z) = \frac{1}{z} - \frac{1}{z-1} + \frac{1}{z+T-1} \rightarrow u(k) = (1 - (1-T)^k)u(k)$

MÉTODOS: FORWARD EULER

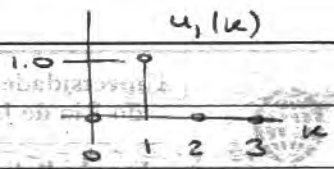
QUESTÃO #2:

$y(3) = 1 - e^{-2} + (-1 + e^{-1}) = e^{-1} - e^{-2}$



$y(0) = 0$ ;  $y(1) = 0$ ;  $y(2) = 1 - e^{-1}$ ;  $y(3) = \checkmark$

b)  $\frac{1-e^{-1}}{z-e^{-1}} = \frac{Y_1(z)}{U_1(z)} \implies y_1(k+1) = (1-e^{-1})u_1(k) + e^{-1}y_1(k)$



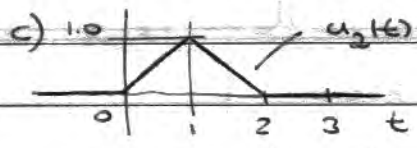
$y_1(0) = (1-e^{-1})x_0 + e^{-1}x_0 = 0$

$y_1(1) = (1-e^{-1})x_0 + e^{-1}x_0 = 0$

$y_1(2) = (1-e^{-1})x_1 + e^{-1}x_0 = (1-e^{-1})$

$y_1(3) = (1-e^{-1})x_0 + e^{-1}(1-e^{-1}) = e^{-1} - e^{-2}$

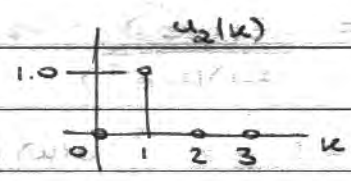
NOTE QUE OS VALORES SÃO IGUAIS AOS CALCULADOS NO ITEM (a).



$y_2(0) = 0; y_2(1) = e^{-1}; y_2(2) = 1 + e^{-2} - 2(e^{-1}) = 1 - 2e^{-1} + e^{-2}$

$y_2(3) = (2 + e^{-3}) - 2(1 + e^{-2}) + e^{-1} = e^{-1} - 2e^{-2} + e^{-3}$

d)  $\frac{e^{-1}z + 1 - 2e^{-1}}{z - e^{-1}} = \frac{Y_2(z)}{U_2(z)}$



$y_2(k+1) = e^{-1}y_2(k+1) + (1-2e^{-1})y_2(k) + e^{-1}y_2(k)$

$y_2(0) = e^{-1}x_0 + (1-2e^{-1})x_0 + e^{-1}x_0 = 0$

$y_2(1) = e^{-1}x_1 + (1-2e^{-1})x_0 + e^{-1}x_0 = e^{-1}$

$y_2(2) = e^{-1}x_0 + (1-2e^{-1})x_1 + e^{-1}x_1 = 1 - 2e^{-1} + e^{-2}$

$y_2(3) = e^{-1}x_0 + (1-2e^{-1})x_0 + e^{-1}(1-2e^{-1} + e^{-2}) = e^{-1} - 2e^{-2} + e^{-3}$

NOTE QUE OS VALORES CALCULADOS SÃO IGUAIS AOS CALCULADOS NO ITEM (c).

EXPLICAÇÃO DE  $G_2(z)$ :

$Y_2(s) = \frac{G(s)}{s^2} = \frac{1}{s^2} = \frac{1}{s^2} + \frac{(-1)}{s} + \frac{1}{s+1} \implies y_2(t) = (t-1 + e^{-t})u(t)$

$y_2(k) = (k-1 + e^{-k})u(k)$  (NOTE QUE  $T=1$ )

$Y_2(z) = \frac{z}{(z-1)^2} - \frac{z}{z-1} + \frac{z}{z-e^{-1}}$

MÉTODO: EQUIVALÊNCIA NA RESPOSTA À RAMPA (FIRST-ORDER HOLD).

$G_2(z) = \left( \frac{(z-1)^2}{z} \right) \left( \frac{z}{(z-1)^2} - \frac{z}{z-1} + \frac{z}{z-e^{-1}} \right)$

$G_2(z) = 1 - (z-1) + \frac{(z-1)^2}{z-e^{-1}} = \frac{z - e^{-1} - z^2 + e^{-1}z + z - e^{-1} + z^2 - z + 1}{z-e^{-1}} = \frac{e^{-1}z + 1 - 2e^{-1}}{z-e^{-1}}$

QUESTÃO #3:

a)  $|zI - \phi + \Gamma u| = \begin{vmatrix} z - e^{-2T} + u_1 & u_2 \\ u_1 & z - e^{-3T} + u_2 \end{vmatrix} = z^2 + (u_1 + u_2 - e^{-2T} - e^{-3T})z + e^{-5T} - u_1 e^{-3T} - u_2 e^{-2T}$





PORTANTO: 
$$\frac{Y(z)}{z(z)} = \frac{2(z-0.78)(z-80.34)}{z^3 - 0.7z^2 + 0.1z} = \frac{2(z-0.78)(z-80.34)}{z(z^2 - 0.7z + 0.1)}$$

OBS.: NOTE O ZERO DE  $\delta(z)$  EM 80.34!

QUESTÃO #4: O ESTIMADOR DE ESTADOS É OTIMIZADO.

a) 
$$\alpha_c(z) = \begin{vmatrix} z - 0.585 & 0.468 \\ -0.078 & z - 0.975 \end{vmatrix} = z^2 - 1.06z + 0.37$$

$$\alpha_c(z) = \begin{vmatrix} z - 0.22 & 3.05 \\ -0.06 & z - 0.84 \end{vmatrix} = z^2 - 1.06z + 0.37$$

b) 
$$\phi - L\phi = \begin{bmatrix} 0.585 & -0.468 \\ 0.078 & 0.975 \end{bmatrix} - \begin{bmatrix} 4.927 & 4.927 \\ -4.150 & -4.150 \end{bmatrix} \begin{bmatrix} 0.585 & -0.468 \\ 0.078 & 0.975 \end{bmatrix}$$

$$= \begin{bmatrix} -2.68 & -2.97 \\ 2.83 & 3.08 \end{bmatrix}$$

$$\alpha_e(z) = \begin{vmatrix} z + 2.68 & 2.97 \\ -2.83 & z - 3.08 \end{vmatrix} = z^2 - 0.4z + 0.15$$

c) 
$$\delta(z) = \begin{vmatrix} z + 1.164 & -7.813 \\ -1.226 & z + 8.305 \end{vmatrix} = z^2 + 9.47z + 0.09$$

$$\theta = \tan^{-1} \left( \frac{0.3}{0.53} \right)$$

d) RAÍZES DE  $\alpha_c(z)$ :  $0.53 \pm 0.3j = 0.61 e^{j\theta}$

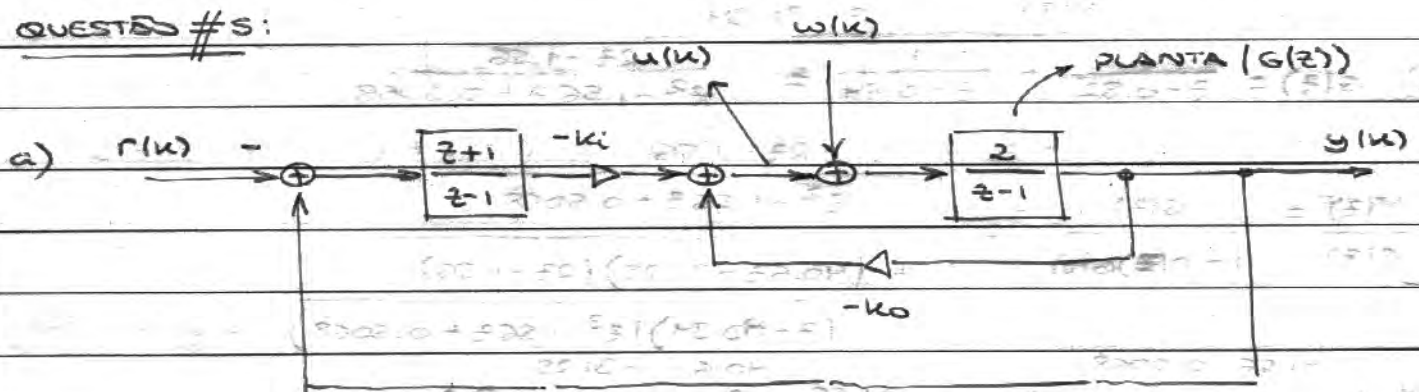
$$\sqrt{0.53^2 + 0.3^2}$$

$$0.61 e^{0.52j} = e^{\sigma T} e^{j\omega T}$$

$$\sigma = -0.49 \rightarrow \tau = -4.9 \rightarrow \tau_s \approx 0.94 \text{ seg}$$

$$\omega T = 0.52 \rightarrow \omega = 5.2 \rightarrow \tau_p \approx 0.60 \text{ seg}$$

QUESTÃO #5:



b) 
$$Y(z) \left( \frac{z-1}{z} \right) = W(z) - k_1 \left( \frac{z+1}{z-1} \right) (Y(z) - R(z)) - k_0 Y(z)$$

$$(z-1)^2 Y = 2(z-1)W - 2k_i z Y + 2k_i R z - 2k_i Y + 2k_i e - k_0 z Y + k_0 Y$$

$$(z^2 - 2z + 1 + 2k_i z + 2k_i + 2k_0 z - k_0) Y = 2(z-1)W + 2k_i(z+1)e$$

$$Y(z) = \frac{(2z-2)W(z) + (2z+2)k_i e(z)}{z^2 + (2k_i + 2k_0 - 2)z + 2k_i \cancel{+1} + 1}$$

$$K_c(z) = (z-0.5)(z-0.2) = z^2 - 0.7z + 0.1$$

$$\text{ENTÃO: } 2k_i + 2k_0 = 1.3$$

$$2k_i - k_0 = -0.9$$

$$3k_0 = 2.2 \rightarrow k_0 = 0.73$$

$$k_i = \frac{-0.9 + 0.73}{2} \rightarrow k_i = -0.09$$

$$c) \frac{Y(z)}{e(z)} = \frac{-0.18(z+1)}{z^2 - 0.7z + 0.1}$$

$$d) \frac{Y(z)}{W(z)} = \frac{2(z-1)}{z^2 - 0.7z + 0.1}$$

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