

QUESTÃO #1:

a) zero: $e^{-0.4} = 0.67$

$$D(z) = \frac{k(z-0.67)}{z^2 - 1.84z + 1}$$

pólos: $e^{\pm 0.4j} = 0.92 \pm 0.39j$

$$\lim_{z \rightarrow 1} D(z) = \lim_{s \rightarrow 0} D(s) \implies 2.06k = 2 \implies k = 0.97$$

$$b) D(z) = \frac{2 \left(\frac{z(z-1)}{T(z+1)} + 1 \right)}{\left(\frac{z(z-1)}{T(z+1)} \right)^2 + 1} = \frac{2(2T(z-1)(z+1) + T^2(z+1)^2)}{4(z-1)^2 + T^2(z+1)^2}$$

$$D(z) = \frac{2(z^2(T^2+2T) + 2T^2z + T^2 - 2T)}{(T^2+4)z^2 + (2T^2-8)z + T^2+4} = \frac{1.92(z^2 + 0.33z - 0.67)}{4.16(z^2 - 1.85z + 1)}$$

$$D(z) = \frac{0.46(z+1)(z-0.67)}{z^2 - 1.85z + 1}$$

c) $\frac{D(s)}{s} = \frac{2(s+1)}{s(s^2+1)} = \frac{A}{s} + \frac{B}{s+j} + \frac{C}{s-j}$

$$A = \frac{2(s+1)}{s^2+1} \Big|_{s=0} = 2 ; \quad B = \frac{2(s+1)}{s(s-j)} \Big|_{s=-j} = \frac{2(1-j)}{(-j)(-2j)} = -1+j ; \quad C = -1-j$$

$$y(t) = (2 + (-1+j)e^{-jt} + (-1-j)e^{jt}) u(t)$$

$$y(k) = (2 + (-1+j)e^{-jTk} + (-1-j)e^{jTk}) u(k)$$

$$Y(z) = \frac{2z}{z-1} + (-1+j) \frac{z}{z-e^{-jT}} + (-1-j) \frac{z}{z-e^{jT}}$$

$$D(z) = 2 + (z-1) \left(\frac{-1+j}{z-e^{-jT}} + \frac{-1-j}{z-e^{jT}} \right)$$

$$\frac{z(-1+j-1-j) + e^{jT} - je^{jT} + e^{-jT} + je^{-jT}}{z^2 - (e^{jT} + e^{-jT})z + 1}$$

$$\frac{-2z + 2\cos(T) + 2\sin(T)}{z^2 - 2\cos(T)z + 1}$$

$$\frac{-2z + 2.62}{z^2 - 1.84z + 1}$$

NOTE QUE:

$$e^{jT} + e^{-jT} = 2\cos(T)$$

$$\sin(T) = \frac{e^{jT} - e^{-jT}}{2j}$$

$$2\sin(T) = je^{-jT} - je^{jT}$$

$$D(z) = 2 + \frac{(z-1)(-2z + 2.62)}{z^2 - 1.84z + 1} = \frac{2z^2 - 3.68z + 2 - 2z^2 + 2.62z + 2z - 2.62}{z^2 - 1.84z + 1}$$

$$D(z) = \frac{0.94z - 0.62}{z^2 - 1.84z + 1}$$

$$D(z) = \frac{0.94(z-0.66)}{z^2 - 1.84z + 1}$$

QUESTÃO # 2:

a) $G(s) = \frac{1}{s} + \frac{(-1)}{s+1}$

FCN: $F = \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}$; $G = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$; $H = [1 \quad -1]$

$\Phi = e^{FT} = \begin{bmatrix} 1 & 0 \\ 0 & e^{-T} \end{bmatrix}$

$\Gamma = \int_0^T \begin{bmatrix} 1 \\ e^{-\sigma} \end{bmatrix} d\sigma = \begin{bmatrix} T \\ 1 - e^{-T} \end{bmatrix}$

$$G(z) = H(zI - \Phi)^{-1} \Gamma = [1 \quad -1] \begin{bmatrix} z^{-1} & 0 \\ 0 & z - e^{-T} \end{bmatrix}^{-1} \begin{bmatrix} T \\ 1 - e^{-T} \end{bmatrix}$$

$$= [1 \quad -1] \begin{bmatrix} z - e^{-T} & 0 \\ 0 & z^{-1} \end{bmatrix} \begin{bmatrix} T \\ 1 - e^{-T} \end{bmatrix}$$

$$\frac{z^2 - (1 + e^{-T})z + e^{-T}}{z^2 - (1 + e^{-T})z + e^{-T}}$$

$G(z) = \frac{z(T + e^{-T} - 1) + 1 - e^{-T} - Te^{-T}}{z^2 - (1 + e^{-T})z + e^{-T}}$

b) $\Phi_{cc} = \begin{bmatrix} e^{-T} + 1 & -e^{-T} \\ 1 & 0 \end{bmatrix}$; $\Gamma_{cc} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$; $H_{cc} = [T + e^{-T} - 1 \quad 1 - e^{-T} - Te^{-T}]$

c) $z = e^{-2 \pm 2j} = -0.06 \pm 0.12j \rightarrow \alpha_c(z) = z^2 + 0.12z + 0.02$

FCC: $k_1 - (1 + e^{-T}) = +0.12 \leftarrow$ POR INSPECÇÃO DO DENOMINADOR DE $G(z)$.

$k_1 - 1.82 = 0.12$

$k_1 = 1.94$

$k_2 + e^{-T} = 0.02 \leftarrow$ POR INSPECÇÃO DO DENOMINADOR DE $G(z)$.

$k_2 + 0.82 = 0.02$

$k_2 = -0.80$

PORTANTO: $K = [1.94 \quad -0.80]$

d) $\frac{Y(z)}{R(z)} = \frac{z(T + e^{-T} - 1) + (1 - e^{-T} - Te^{-T})}{z^2 + 0.12z + 0.02} = \frac{0.02z + 0.02}{z^2 + 0.12z + 0.02}$

$(T + e^{-T} - 1 = 0.02 \quad \text{e} \quad 1 - e^{-T} - Te^{-T} = 0.02)$

SENHO DC: $\lim_{z \rightarrow 1} \frac{Y(z)}{R(z)} = \frac{0.02 + 0.02}{1 + 0.12 + 0.02} = 0.035$

QUESTÃO #3:

a) $\bar{\Phi} = \begin{bmatrix} 1 & 1 \\ -0.5 & 0 \end{bmatrix}$; $\Gamma = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix}$; $H = [1 \ 0]$; $x(k+1) = \bar{\Phi}x(k) + u(k)$
 $y(k) = Hx(k)$

b) $|zI - \bar{\Phi} + \Gamma K| = \begin{vmatrix} z-1+k_1 & -1+k_2 \\ 0.5+0.5k_1 & z+0.5k_2 \end{vmatrix} = z^2 + (k_1 + 0.5k_2 - 1)z + 0.5k_1k_2 - 0.5k_2$
 $+ 0.5 + 0.5k_1 - 0.5k_2 - 0.5k_1k_2$
 $= z^2 + (k_1 + 0.5k_2 - 1)z + 0.5k_1 - k_2 + 0.5$

$\alpha_c(z) = (z - 0.25 - 0.25j)(z - 0.25 + 0.25j) = z^2 - 0.5z + 0.125$

$|zI - \bar{\Phi} + \Gamma K| = \alpha_c(z) \Rightarrow \begin{cases} k_1 + 0.5k_2 = 0.5 \\ 0.5k_1 - k_2 = -0.375 \end{cases} \rightarrow \begin{cases} k_1 - 2k_2 = -0.75 \\ 2.5k_2 = 1.25 \end{cases} \rightarrow k_2 = 0.5$

$k_1 = -0.75 + 2k_2 \rightarrow k_1 = 0.25$

$K = [0.25 \ 0.5]$

c) $\begin{array}{cc} \bar{\Phi}_{aa} & \bar{\Phi}_{ab} \\ \left[\begin{array}{c|c} 1 & 1 \\ -0.5 & 0 \end{array} \right] & \begin{array}{c} \Gamma_a \\ \left[\begin{array}{c} 1 \\ 0.5 \end{array} \right] \\ \Gamma_b \end{array} \\ \bar{\Phi}_{ba} & \bar{\Phi}_{bb} \end{array}$

$z+L = z+0.1$

$z - \bar{\Phi}_{bb} + L\bar{\Phi}_{ab} = z+L \rightarrow L = 0.1$

$\alpha_e(z) = z + 0.1$

d) $\hat{x}_2(k+1) = (\bar{\Phi}_{ba} - L\bar{\Phi}_{aa})y(k) + Ly(k+1) + (\bar{\Phi}_{bb} - L\bar{\Phi}_{ab})\hat{x}_2(k) + (\Gamma_b - L\Gamma_a)u(k)$

$\bar{\Phi}_{ba} - L\bar{\Phi}_{aa} = -0.6$

$u(k) = -0.25y(k) - 0.5\hat{x}_2(k)$

$\bar{\Phi}_{bb} - L\bar{\Phi}_{ab} = -0.1$

$\Gamma_b - L\Gamma_a = 0.4$

ENTÃO: $\hat{x}_2(k+1) = -0.6y(k) + 0.1y(k+1) - 0.1\hat{x}_2(k) - 0.1y(k) - 0.2\hat{x}_2(k)$

$\hat{x}_2(k+1) = -0.3\hat{x}_2(k) - 0.7y(k) + 0.1y(k+1)$

e) $X_2(z) = \frac{(0.1z - 0.7) \cdot Y(z)}{z + 0.3}$

$U(z) = -0.25Y(z) - 0.5 \frac{(0.1z - 0.7)Y(z)}{z + 0.3} = \frac{(-0.25z - 0.075 - 0.05z + 0.35)Y(z)}{z + 0.3}$

$D(z) = \frac{U(z)}{Y(z)} = \frac{-0.3z + 0.275}{z + 0.3}$

OBS.: $\frac{Y(z)}{R(z)} = \frac{z+0.5}{z^2 - z + 0.5} \cdot \frac{1}{1 - (z+0.5)(-0.3z + 0.275)}$
 $\frac{Y(z)}{R(z)} = \frac{(z+0.5)(z+0.3)}{z^3 - z^2 + 0.5z + 0.3z^2 - 0.3z + 0.15 + 0.3z^2 - 0.275z + 0.15z - 0.1375}$

$\frac{Y(z)}{R(z)} = \frac{z^2 + 0.8z + 0.15}{z^3 - 0.4z^2 + 0.075z + 0.0125} = \frac{(z+0.5)(z+0.3)}{(z+0.1)(z^2 - 0.5z + 0.125)}$

$\frac{Y(z)}{R(z)} = \frac{z^2 + 0.8z + 0.15}{z^3 - 0.4z^2 + 0.075z + 0.0125} = \frac{(z+0.5)(z+0.3)}{(z+0.1)(z^2 - 0.5z + 0.125)}$

\downarrow $\alpha_e(z)$ \downarrow $\alpha_c(z) \checkmark$

QUESTÃO #4:

a) $x(k+1) = \bar{\phi}x(k) + \Gamma u(k)$, ONDE $\bar{\phi} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$, $\Gamma = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, $H = [1 \ 0 \ 0]$
 $y(k) = Hx(k)$

NO FCO, OBTÉM-SE $|zI - \bar{\phi} + LH|$ POR INSPECÇÃO:

$$|zI - \bar{\phi} + LH| = z^3 + e_1 z^2 + e_2 z + (-1 + e_3)$$

$$\alpha_e(z) = z^3$$

$$\alpha_e(z) = |zI - \bar{\phi} + LH| \Rightarrow e_1 = 0, e_2 = 0 \text{ e } e_3 = 1. \quad L = L_p = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

b) $L_a = \bar{\phi}^{-1} L_p = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \Rightarrow L_a = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ (~~$L_a = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$~~)

c) EQUAÇÃO DO ESTIMADOR DE PREDIÇÃO (SUBSTITUINDO $u = -k\hat{x}$):

$$\hat{x}(k+1) = (\bar{\phi} - LH - \Gamma k) \hat{x}(k) + L y(k)$$

$$u(k+1) = -k \hat{x}(k+1)$$

COMPARANDO COM O PSEUDO-CÓDIGO:

$$A = \bar{\phi} - LH - \Gamma k = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} [1 \ 0 \ 0] - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} [1 \ 0 \ 0] = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & 0 \end{bmatrix}$$

$$B = L = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$C = -k \Rightarrow C = [-1 \ 0 \ 0]$$

d) EQUAÇÃO DO ESTIMADOR ATUALIZADO (SUBSTITUINDO $u = -k\hat{x}$):

$$\hat{x}(k) = \underbrace{(\bar{\phi} - LH\bar{\phi} - \Gamma k + LH\Gamma k)}_{\check{x}(k)} \hat{x}(k-1) + L y(k)$$

$$u(k) = -k \hat{x}(k)$$

$$\check{x}(k+1) = (\bar{\phi} - LH\bar{\phi} - \Gamma k + LH\Gamma k) \hat{x}(k)$$

COMPARANDO COM O PSEUDO-CÓDIGO:

$$X = L = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}; \quad Y = -k \Rightarrow Y = [-1 \ 0 \ 0]$$

$$\check{z} = \bar{\phi} - LH\bar{\phi} - \Gamma k + LH\Gamma k = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\bar{\phi} - LH\bar{\phi} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} [0 \ 1 \ 0] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$$\Gamma - LH\Gamma = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} [1 \ 0 \ 0] = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$(\Gamma - LH\Gamma)k = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} [1 \ 0 \ 0] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

QUESTÃO #5:

a) $x_{i1}(u+1) = x_{i1}(u) + e(u) \longrightarrow x_{i1}(u+1) = x_{i1}(u) + x(u) - r(u)$

$x_{i2}(u+1) = x_{i2}(u) + x_{i1}(u)$

$x(u+1) = 0.2x(u) + u(u) + w(u) \longrightarrow x(u+1) = 0.2x(u) + w(u) - k_{i1}x_{i1}(u) - k_{i2}x_{i2}(u) - k_0x(u)$

$$\begin{bmatrix} x_{i1}(u+1) \\ x_{i2}(u+1) \\ \cancel{x(u+1)} \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ -k_{i1} & -k_{i2} & 0.2 - k_0 \end{bmatrix}}_{\Phi_i - \Gamma_i^T k} \begin{bmatrix} x_{i1}(u) \\ x_{i2}(u) \\ x(u) \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} r(u) + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} w(u)$$

(*)

(*): OBS.: $y(u) = [0 \ 0 \ 1] \begin{bmatrix} x_{i1}(u) \\ x_{i2}(u) \\ x(u) \end{bmatrix}$

b) $|zI - \Phi_i + \Gamma_i^T k| = \begin{vmatrix} z-1 & 0 & -1 \\ -1 & z-1 & 0 \\ k_{i1} & k_{i2} & z-0.2+k_0 \end{vmatrix} = (z^2 - 2z + 1)(z - 0.2 + k_0) + k_{i2} + k_{i1}z - k_{i1}$

$= z^3 - 2z^2 + z - 0.2z^2 + k_0z^2 + 0.4z - 2k_0z - 0.2 + k_0 + k_{i2} + k_{i1}z - k_{i1}$

$= z^3 + (k_0 - 2.2)z^2 + (k_{i1} - 2k_0 + 1.4)z + k_0 + k_{i2} - k_{i1} - 0.2 = 0$

DESD. BEST: $\alpha_c(z) = z^3 \implies k_0 = 2.2$

$k_{i1} - 4.4 + 1.4 = 0 \implies k_{i1} = 3$

$2.2 + k_{i2} - 3 - 0.2 = 0 \implies k_{i2} = 1$

PORTANTO $k = [3 \ 1 \ 2.2]$

c) USANDO $k = [3 \ 1 \ 2.2]$: $\Phi_i - \Gamma_i^T k = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ -3 & -1 & -2 \end{bmatrix}$

$\frac{Y(z)}{R(z)} = [0 \ 0 \ 1] \begin{bmatrix} z-1 & 0 & -1 \\ -1 & z-1 & 0 \\ 3 & 1 & z+2 \end{bmatrix}^{-1} \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} = \frac{(-1-3z+3)(-1)}{z^3} \implies \frac{Y(z)}{R(z)} = \frac{3z-2}{z^3}$

d) $\frac{Y(z)}{W(z)} = [0 \ 0 \ 1] \begin{bmatrix} z-1 & 0 & -1 \\ -1 & z-1 & 0 \\ 3 & 1 & z+2 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \frac{(z-1)^2}{z^3}$

$\frac{Y(z)}{W(z)} = \frac{(z-1)^2}{z^3}$