

Gabarito Lista #8 — Controle II

a) PÓLOS : $s_1 = -2, s_2 = -3 \rightarrow z_1 = e^{-2T}, z_2 = e^{-3T}$

zeros : ~~zeros~~, ~~zeros~~ $\rightarrow z_3 = e^{-T}, z_4 = e^{-4T}$
 $s_3 = -1, s_4 = -4$

$D(z) = \frac{(z - e^{-T})(z - e^{-4T})}{(z - e^{-2T})(z - e^{-3T})} \cdot k$

$\lim_{z \rightarrow 1} D(z) = \frac{(1 - e^{-T})(1 - e^{-4T})}{(1 - e^{-2T})(1 - e^{-3T})} k = \frac{4}{6} \rightarrow k = \frac{(1 - e^{-2T})(1 - e^{-3T})}{(1 - e^{-T})(1 - e^{-4T})} \cdot \frac{4}{6}$

ENTÃO: $D(z) = \frac{4}{6} \frac{(1 - e^{-2T})(1 - e^{-3T})}{(1 - e^{-T})(1 - e^{-4T})} \frac{(z^2 - z(e^{-T} + e^{-4T}) + e^{-5T})}{(z^2 - z(e^{-2T} + e^{-3T}) + e^{-5T})}$

b) $D(z) = D(s) \Big|_{s = \frac{z-1}{T}} = \frac{\left(\frac{z-1}{T} + 1\right)\left(\frac{z-1}{T} + 4\right)}{\left(\frac{z-1}{T} + 2\right)\left(\frac{z-1}{T} + 3\right)} = \frac{(z-1+T)(z-1+4T)}{(z-1+2T)(z-1+3T)}$

$D(z) = \frac{z^2 + (\frac{5}{T} - 2)z + 1 - 5T + 4T^2}{z^2 + (\frac{5}{T} - 2)z + 1 - 5T + 6T^2}$

c) $D(z) = D(s) \Big|_{s = \frac{z-1}{Tz}} = \frac{\left(\frac{z-1}{Tz} + 1\right)\left(\frac{z-1}{Tz} + 4\right)}{\left(\frac{z-1}{Tz} + 2\right)\left(\frac{z-1}{Tz} + 3\right)} = \frac{((T+1)z-1)((4T+1)z-1)}{((2T+1)z-1)((3T+1)z-1)}$

$D(z) = \frac{4T^2}{(2T+1)z-1} - \frac{1}{(3T+1)z-1}$

d) $D(z) = D(s) \Big|_{s = \frac{z-1}{T(z+1)}} = \frac{\left(\frac{z-1}{T(z+1)} + 1\right)\left(\frac{z-1}{T(z+1)} + 4\right)}{\left(\frac{z-1}{T(z+1)} + 2\right)\left(\frac{z-1}{T(z+1)} + 3\right)} = \frac{((T+2)z+T-2)((4T+2)z+4T-2)}{((2T+2)z+2T-2)((3T+2)z+3T-2)}$

$D(z) = \frac{(4T^2 + 10T + 4)z^2 + (\frac{8}{T} - 8)z + 4T^2 - 10T + 4}{(6T^2 + 10T + 4)z^2 + (12T^2 - 8)z + 6T^2 - 10T + 4}$

e) $\frac{D(s)}{s} = \frac{(s+1)(s+4)}{s(s+2)(s+3)} = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+3} = \frac{2/3}{s} + \frac{1}{s+2} - \frac{2/3}{s+3}$
 $A = \frac{4}{6}, B = \frac{-2}{-2} = 1, C = \frac{-2}{3}$
 $A = \frac{2}{3}$

$d^{-1}\left(\frac{D(s)}{s}\right) = \left(\frac{2}{3} + e^{-2t} - \frac{2}{3}e^{-3t}\right)u(t) = u(t) \leftarrow$ SINAL DE CONTROLE
 DESAÍDO UNITÁRIO \rightarrow DIFERENTES! (INDEFINIDAMENTE COM A LETRA).

$u(k) = \left(\frac{2}{3} + e^{-2Tk} - \frac{2}{3}e^{-3Tk}\right)u(k)$

$U(z) = \frac{2}{3} \cdot \frac{z}{z-1} + \frac{z}{z - e^{-2T}} - \frac{2}{3} \cdot \frac{z}{z - e^{-3T}}$

$D(z) = \frac{z-1}{z} U(z) = \frac{2}{3} + \frac{z-1}{z - e^{-2T}} - \frac{2}{3} \frac{z-1}{z - e^{-3T}} = \frac{\frac{2}{3}(z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}) + (z-1)(z - e^{-3T}) - \frac{2}{3}(z^2 - (e^{-2T} + e^{-3T})z + e^{-5T})}{(z^2 - (e^{-2T} + e^{-3T})z + e^{-5T})}$

$$D(z) = \frac{\frac{2}{3}(z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}) + z^2 - (1 + e^{-3T})z + e^{-3T} - \frac{2}{3}(z^2 - (1 + e^{-2T})z + e^{-2T})}{z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}}$$

$$D(z) = \frac{z^2 + \left(\frac{-1}{3} - \frac{5}{3}e^{-3T}\right)z + \left(\frac{2e^{-5T}}{3} + e^{-3T} - \frac{2}{3}e^{-2T}\right)}{z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}}$$

$$f) D(s) = \frac{(s+1)(s+4)}{(s+2)(s+3)} = \frac{A}{s+2} + \frac{B}{s+3} = \frac{s^2 + 5s + 4}{s^2 + 5s + 6} = 1 - \frac{2}{s^2 + 5s + 6}$$

$$A = \frac{-2}{1} = -2 \quad B = \frac{-2}{-1} = 2$$

$$\begin{cases} x' = Fx + Gx \\ u = Hx + Jx \end{cases}, \text{ onde } F = \begin{bmatrix} -2 & 0 \\ 0 & -3 \end{bmatrix}, G = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, H = [-2 \quad 2], J = 1$$

(COMPENSADOR)

$$1 + \frac{A}{s+2} + \frac{B}{s+3}$$

$$A = \frac{-2}{1} = -2$$

$$B = \frac{-2}{-1} = 2$$

$$\Phi = e^{FT} = \begin{bmatrix} e^{-2T} & 0 \\ 0 & e^{-3T} \end{bmatrix}$$

$$\Gamma = \int_0^T e^{F(T-\tau)} G d\tau = \int_0^T \begin{bmatrix} e^{-2(T-\tau)} & 0 \\ 0 & e^{-3(T-\tau)} \end{bmatrix} d\tau = \begin{bmatrix} -\frac{1}{2}e^{-2T} & 0 \\ 0 & -\frac{1}{3}e^{-3T} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{3} \end{bmatrix} e^{-2T}$$

$$D(z) = H(zI - \Phi)^{-1} \Gamma + J$$

$$(zI - \Phi)^{-1} = \begin{bmatrix} z - e^{-2T} & 0 \\ 0 & z - e^{-3T} \end{bmatrix}^{-1} = \begin{bmatrix} z - e^{-3T} & 0 \\ 0 & z - e^{-2T} \end{bmatrix}$$

$$z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}$$

ENTÃO:

$$D(z) = [-2 \quad 2] \begin{bmatrix} z - e^{-3T} & 0 \\ 0 & z - e^{-2T} \end{bmatrix} \begin{bmatrix} \frac{1}{2}(1 - e^{-2T}) \\ \frac{1}{3}(1 - e^{-3T}) \end{bmatrix} + 1$$

$$= \frac{-2(1 - e^{-2T})(z - e^{-3T}) + 2(1 - e^{-3T})(z - e^{-2T})}{z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}} + 1$$

$$D(z) = \frac{z^2 + \left(-1 + \frac{2}{3}e^{-2T} - \frac{2}{3}e^{-3T} - e^{-2T} - e^{-3T}\right)z + \left(e^{-3T} - \frac{2}{3}e^{-5T} - \frac{2}{3}e^{-5T} + \frac{2}{3}e^{-5T} + e^{-5T}\right)}{z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}}$$

$$D(z) = \frac{z^2 + \left(\frac{-1}{3} - \frac{5}{3}e^{-3T}\right)z + \left(\frac{2}{3}e^{-5T} + e^{-3T} - \frac{2}{3}e^{-2T}\right)}{z^2 - (e^{-2T} + e^{-3T})z + e^{-5T}} \quad \text{[OK]: IGUAL AO ITEM (2e)}$$

②

NA PÁGINA SEQUINTE...

2) $D(s) = \frac{1}{s + \cancel{\Omega_c}}$ → FREQ. DE CORTE Ω_c

$D(z) = D(s)$

$$r = \frac{z-1}{T} \Rightarrow \frac{z-1}{T} = \frac{z-1}{T} + \cancel{\Omega_c}$$

$$D(e^{j\omega}) = \frac{1}{\frac{z-1}{T} + \cancel{\Omega_c}} = \frac{1}{j\frac{2}{T} \tan\left(\frac{\omega}{2}\right) + \cancel{\Omega_c}}$$

$$\frac{e^{j\omega} - 1}{e^{j\omega} + 1} = \frac{e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}}{e^{j\frac{\omega}{2}} + e^{-j\frac{\omega}{2}}} = j \frac{\sin\left(\frac{\omega}{2}\right)}{\cos\left(\frac{\omega}{2}\right)} = j \tan\left(\frac{\omega}{2}\right)$$

ISTO JÁ FOI FEITO EM OUTRO

$\Omega_c = \frac{2}{T} \tan\left(\frac{\omega_c}{2}\right)$

FREQÜÊNCIA DE CORTE ω_c → A PARTIR DE 1): $\frac{2}{T} \tan\left(\frac{\omega_c}{2}\right) = \cancel{\Omega_c}$

~~$\frac{2}{T} \tan\left(\frac{\omega_c}{2}\right) = \Omega_c$~~

$\Omega_c = \frac{2}{T} \tan\left(\frac{\pi}{6}\right)$

$\Omega_c = \frac{200\sqrt{3}}{3} = 115.5 \text{ rad/seg}$

~~... $\Omega_c = \frac{2}{T} \tan\left(\frac{\omega_c}{2}\right)$...~~

ENTÃO, $\Omega_c = \cancel{\Omega_c}$ PORQUE $\omega_c = \cancel{\omega_c}$. (PRÉ-WARPING).

VERIFICAÇÃO DAS FREQÜÊNCIAS DE CORTE (OPCIONAL).

OBS.: $D(s) = \frac{1}{s + 115.5}$ → $D(z) = \frac{1}{\frac{z-1}{T} + 115.5} = \frac{T}{(z-1) + 115.5T}$

$$D(z) = \frac{0.01z + 0.01}{3.155z - 0.845}$$

VERIFICANDO: $\lim_{z \rightarrow 1} D(z) = \frac{0.02}{2.31} = 8.658 \times 10^{-3} = G_0$

~~...~~

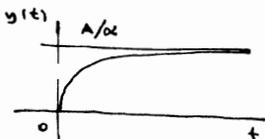
$$D(z) \Big|_{z=e^{j\frac{\pi}{3}}} = \frac{0.01e^{j\frac{\pi}{3}} + 0.01}{3.155e^{j\frac{\pi}{3}} - 0.845} = (4.33 - 4.33j) \times 10^{-3} = a_1$$

3) $u(t) = Ae^{-\alpha t} u(t)$
 $U(s) = \frac{A}{s + \alpha}$

INTEGRANDO: $U(s) \xrightarrow{s^{-1}}$ $y(s) = \frac{A}{s(s + \alpha)} = \frac{B}{s} + \frac{C}{s + \alpha} = \frac{A/\alpha}{s} - \frac{A/\alpha\alpha}{s + \alpha}$

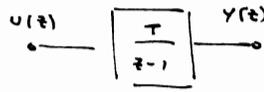
$$B = \frac{A}{\alpha} \quad C = \frac{A}{-\alpha}$$

$$y(t) u(t) = \left(\frac{A}{\alpha} - \frac{A}{\alpha} e^{-\alpha t} \right) u(t) = \frac{A}{\alpha} (1 - e^{-\alpha t}) u(t)$$



$u(kT) = A(e^{-\alpha T})^k \Rightarrow u(k) = Ae^{-\alpha kT} u(k) \Rightarrow U(z) = \frac{Az}{z - e^{-\alpha T}}$

• INTEGRADOR RETANGULAR I (FORWARD EULER):



$$\frac{Y(z)}{U(z)} = \frac{T}{z-1}$$

$$y(k) = y(k-1) + Tu(k-1)$$

$$Y(z) = \frac{Az}{z - e^{-\alpha T}} \cdot \frac{T}{z-1}$$

$$\frac{Y(z)}{z} = \frac{AT}{(z - e^{-\alpha T})(z-1)} = \frac{B}{z - e^{-\alpha T}} + \frac{C}{z-1}$$

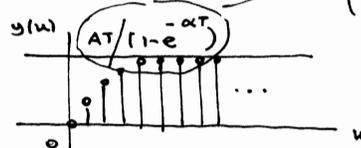
$$B = \frac{AT}{e^{-\alpha T} - 1} = -\gamma$$

$$C = \frac{AT}{1 - e^{-\alpha T}} = \gamma$$

$$Y(z) = \frac{-\gamma z}{z - e^{-\alpha T}} + \frac{\gamma z}{z-1}$$

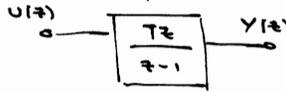
$$y(k) = (\gamma - \gamma e^{-\alpha T k}) u(k) = \gamma (1 - e^{-\alpha T k}) u(k)$$

$$y(k) = \frac{AT}{1 - e^{-\alpha T}} (1 - e^{-\alpha T k}) u(k)$$



$\lim_{T \rightarrow 0} \frac{AT}{1 - e^{-\alpha T}} = \frac{A}{\alpha}$
(L'HOPITAL)

• INTEGRADOR RETANGULAR II (BACKWARD EULER):



$$\frac{Y(z)}{U(z)} = \frac{Tz}{z-1}$$

$$y(k) = y(k-1) + Tu(k)$$

$$Y(z) = \frac{Az}{z - e^{-\alpha T}} \cdot \frac{Tz}{z-1}$$

$$\frac{Y(z)}{z} = \frac{ATz}{(z - e^{-\alpha T})(z-1)} = \frac{B}{z - e^{-\alpha T}} + \frac{C}{z-1}$$

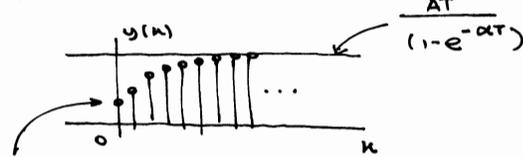
$$B = \frac{ATe^{-\alpha T}}{e^{-\alpha T} - 1} = -\gamma e^{-\alpha T}$$

$$C = \frac{AT}{1 - e^{-\alpha T}} = \gamma$$

$$Y(z) = \frac{-\gamma e^{-\alpha T} z}{z - e^{-\alpha T}} + \frac{\gamma z}{z-1}$$

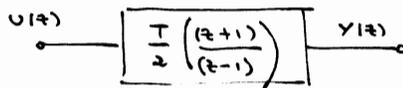
$$y(k) = (\gamma - \gamma e^{-\alpha T} e^{-\alpha T k}) u(k) = \gamma (1 - e^{-\alpha T(k+1)}) u(k)$$

$$y(k) = \frac{AT}{1 - e^{-\alpha T}} (1 - e^{-\alpha T(k+1)}) u(k)$$



RESULTADO OBTENIDO DE 1 ANTES.

• INTEGRADOR TRAPEZOIDAL (TUSTIN):



$$\frac{Y(z)}{U(z)} = \frac{T}{2} \frac{z+1}{z-1}$$

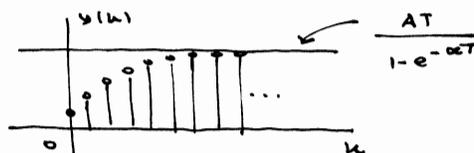
$$y(k) = y(k-1) + \frac{T}{2} (u(k-1) + u(k))$$

$$Y(z) = \frac{Az}{z - e^{-\alpha T}} \cdot \frac{T}{2} \frac{z+1}{z-1}$$

NOTE QUE $Y(z) = \frac{1}{2} \left(\frac{ATz^2}{(z - e^{-\alpha T})(z-1)} + \frac{ATz}{(z - e^{-\alpha T})(z-1)} \right)$

ENTÃO: $y(k) = \frac{1}{2} \left(y_{\text{BACKWARD EULER}}(k) + y_{\text{FORWARD EULER}}(k) \right)$

$$y(k) = \frac{AT}{1 - e^{-\alpha T}} \left(1 - \frac{1}{2} (e^{-\alpha T k} + e^{-\alpha T(k+1)}) \right) u(k)$$



• OBTÉM-SE O MÉDIO DOS RESULTADOS DOS OUTROS DOIS MÉTODOS.

4) a) $F = \begin{bmatrix} -2 & -2 \\ 1 & 0 \end{bmatrix}$ $G = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ $H = [1 \ 1]$

$$e^{Ft} = \mathcal{L}^{-1} \left[(sI - F)^{-1} \right]$$

$$(sI - F)^{-1} = \begin{bmatrix} s+2 & 2 \\ -1 & s \end{bmatrix}^{-1} = \frac{\begin{bmatrix} s & -2 \\ 1 & s+2 \end{bmatrix}}{s^2 + 2s + 2} = \begin{bmatrix} \cancel{A} & \cancel{A} \\ \cancel{A} & \cancel{A} \end{bmatrix}$$

OBS.: $A(s) = \frac{s+1}{s^2+2s+2} \longleftrightarrow a(t) = e^{-t} \cos t u(t)$

$B(s) = \frac{1}{s^2+2s+2} \longleftrightarrow b(t) = e^{-t} \sin t u(t)$

$A_{11}(s) = \frac{s}{s^2+2s+2} \longrightarrow a_{11}(t) = e^{-t} (\cos t - \sin t) u(t)$

$A_{12}(s) = \frac{-2}{s^2+2s+2} \longrightarrow a_{12}(t) = -2e^{-t} \sin t u(t)$

$A_{21}(s) = \frac{1}{s^2+2s+2} \longrightarrow a_{21}(t) = e^{-t} \sin t u(t)$

$A_{22}(s) = \frac{s+2}{s^2+2s+2} \longrightarrow a_{22}(t) = e^{-t} (\cos t + \sin t) u(t)$

ENTRÒ: $e^{Ft} = \begin{bmatrix} e^{-t}(\cos t - \sin t) u(t) & -2e^{-t} \sin t u(t) \\ e^{-t} \sin t u(t) & e^{-t}(\cos t + \sin t) u(t) \end{bmatrix} \longrightarrow \Phi = e^{Ft} = \begin{bmatrix} e^{-T}(\cos T - \sin T) & -2e^{-T} \sin T \\ e^{-T} \sin T & e^{-T}(\cos T + \sin T) \end{bmatrix}$

$\Gamma = \int_0^T e^{Ft} G dt = \int_0^T \begin{bmatrix} e^{-t}(\cos t - \sin t) \\ e^{-t} \sin t \end{bmatrix} dt = \begin{bmatrix} e^{-T} \sin T \\ \frac{1}{2}(1 - e^{-T} \cos T - e^{-T} \sin T) \end{bmatrix}$

OBS.: $\int_0^T e^{-t} \cos t dt = \frac{1}{2}(1 - e^{-T} \cos T + e^{-T} \sin T)$

$\int_0^T e^{-t} \sin t dt = \frac{1}{2}(1 - e^{-T} \cos T - e^{-T} \sin T)$

$\Phi = \begin{bmatrix} a-b & -2b \\ b & a+b \end{bmatrix}$ $\Gamma = \begin{bmatrix} b \\ \frac{1}{2}(1-a-b) \end{bmatrix}$ $H = [1 \ 1]$ $\begin{pmatrix} a = e^{-T} \cos T \\ b = e^{-T} \sin T \end{pmatrix}$

$D(z) = H(zI - \Phi)^{-1} \Gamma$

$(zI - \Phi)^{-1} = \begin{bmatrix} z-a+b & 2b \\ -b & z-a-b \end{bmatrix}^{-1} = \frac{\begin{bmatrix} z-a-b & -2b \\ b & z-a+b \end{bmatrix}}{z^2 - 2az + a^2 + b^2}$

$H(zI - \Phi)^{-1} = [1 \ 1] \frac{\begin{bmatrix} z-a-b & -2b \\ b & z-a+b \end{bmatrix}}{z^2 - 2az + a^2 + b^2} = \frac{[z-a \ z-a-b]}{z^2 - 2az + a^2 + b^2}$

$H(zI - \Phi)^{-1} \Gamma = [z-a \ z-a-b] \frac{\begin{bmatrix} b \\ \frac{1}{2}(1-a-b) \end{bmatrix}}{z^2 - 2az + a^2 + b^2} = \frac{\left(\frac{1}{2} - \frac{a}{2} + \frac{b}{2}\right)z + \left(\frac{a^2}{2} + \frac{b^2}{2} - \frac{a-b}{2}\right)}{z^2 - 2az + a^2 + b^2}$

$\frac{b^2 - ab + \frac{z}{2} - \frac{a-b}{2} - \frac{az}{2} + \frac{a^2}{2} + \frac{ab}{2} - \frac{bz}{2} + \frac{ab}{2} + \frac{b^2}{2}}{z^2 - 2az + a^2 + b^2}$

$H(zI - \Phi)^{-1} \Gamma = \frac{1}{2} \cdot \frac{(1-a+b)z + (a^2+b^2-a-b)}{z^2 - 2az + a^2 + b^2}$

ENTRÒ: $D(z) = 0.5 \left[\frac{(1 + e^{-T}(\sin T - \cos T))z + (e^{-2T} + e^{-T}(-\cos T - \sin T))}{z^2 - (2e^{-T} \cos T)z + e^{-2T}} \right]$

$$b) D(z) = D(s) \left|_{s = \frac{z(z-1)}{T(z+1)}} = \frac{\frac{z(z-1)}{T(z+1)} + 1}{\left(\frac{z(z-1)}{T(z+1)}\right)^2 + 2 \cdot \frac{z(z-1)}{T(z+1)} + 2}$$

$$D(z) = \frac{z(z-1)T(z+1) + T^2(z+1)^2}{4(z-1)^2 + 4(z-1)T(z+1) + 2T^2(z+1)^2}$$

$$D(z) = \frac{2Tz^2 - 2Tz + T^2z^2 + 2T^2z + T^2}{4z^2 - 8z + 4 + 4Tz^2 - 4Tz + 2T^2z^2 + 4T^2z + 2T^2}$$

$$D(z) = \frac{(T^2 + 2T)z^2 + 2T^2z + T^2 - 2T}{(2T^2 + 4T + 4)z^2 + (4T^2 - 8)z + 2T^2 - 4T + 4}$$

— • SOME OFS PROBLEMS ④ (CONTEÚTOS) E ⑤ — VER PÁGINAS SEQUENTES ...

— " — " —

Lista #8 - Questao #4 - Comentario sobre as aproximacoes

V=[0.001 0.002 0.005 0.010 0.020 0.050 0.100 0.200 0.500 1.000];

M=[];

for k=1:length(V),

 T=V(k);

 nd=0.5*[0 1+exp(-T)*(sin(T)-cos(T)) exp(-2*T)+exp(-T)*(-cos(T)-sin(T))];

 dd=[1 -2*exp(-T)*cos(T) exp(-2*T)];

 nb=[T^2+2*T 2*T^2 T^2-2*T]/(2*T^2+4*T+4);

 db=[2*T^2+4*T+4 4*T^2-8 2*T^2-4*T+4]/(2*T^2+4*T+4);

 M=[M ; nd dd nb db [roots(nd)' roots(dd)' roots(nb)' roots(db)'] log([roots(nd)' roots(dd)' roots(nb)' roots(db)']/T)];

end;

[V ; transpose(M)]

ans =

T

0.0500	0.1000	0.2000	0.5000	1.0000
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Discretizacao (numerador)

0	0	0	0	0
0.0488	0.0950	0.1801	0.3793	0.5554
-0.0464	-0.0860	-0.1474	-0.2276	-0.1865

Discretizacao (denominador)

1.0000	1.0000	1.0000	1.0000	1.0000
-1.9001	-1.8006	-1.6048	-1.0646	-0.3975
0.9048	0.8187	0.6703	0.3679	0.1353

Bilinear (numerador)

0.0244	0.0475	0.0902	0.1923	0.3000
0.0012	0.0045	0.0164	0.0769	0.2000
-0.0232	-0.0430	-0.0738	-0.1154	-0.1000

Bilinear (denominador)

1.0000	1.0000	1.0000	1.0000	1.0000
-1.9001	-1.8009	-1.6066	-1.0769	-0.4000
0.9049	0.8190	0.6721	0.3846	0.2000

Discretizacao (polos)

0.9500 - 0.0475i	0.9003 - 0.0903i	0.8024 - 0.1627i	0.5323 - 0.2908i	0.1988 - 0.3096i
0.9500 + 0.0475i	0.9003 + 0.0903i	0.8024 + 0.1627i	0.5323 + 0.2908i	0.1988 + 0.3096i

Bilinear (polos)

0.9501 - 0.0476i	0.9005 - 0.0905i	0.8033 - 0.1639i	0.5385 - 0.3077i	0.2000 - 0.4000i
0.9501 + 0.0476i	0.9005 + 0.0905i	0.8033 + 0.1639i	0.5385 + 0.3077i	0.2000 + 0.4000i

Discretizacao (zeros)

0.9512	0.9048	0.8182	0.6001	0.3358
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Bilinear (zeros)

-1.0000	-1.0000	-1.0000	-1.0000	-1.0000
0.9512	0.9048	0.8182	0.6000	0.3333

Note que, `a medida em que T diminui, os resultados da aproximacao bilinear aproximam-se dos resultados da discretizacao no espaco de estados. A aproximacao bilinear possui um zero a mais, em z=-1.

Lista #8 - Questao #5

format long

```
V=[0.05 0.10 0.50 1.00 5.00 10.0];
M=[];
```

for k=1:length(V),

T=V(k);

% Mapeamento polos e zeros

```
A=[roots([1 -(exp(-T)+exp(-4*T)) exp(-5*T)]); roots([1 -(exp(-2*T)+exp(-3*T)) exp(-5*T)])]
```

% Forward Euler

```
B=[roots([1 5*T-2 1-5*T+4*T^2]) ; roots([1 5*T-2 1-5*T+6*T^2])]
```

% Backward Euler

```
C=[roots([T^2+5*T+4 -(S*T+2) 1]) ; roots([T^2+5*T+6 -(S*T+2) 1])] ← VER CORREÇÃO FEITA NO RESPOSTA (C)
```

% Bilinear

```
D=[roots([4*T^2+10*T+4 8*T^2-8 4*T^2-10*T+4]) ; roots([6*T^2+10*T+4 12*T^2-8 6*T^2-10*T+4])]
```

% Equivalencia Degrau, ou Discretizacao (mesmo resultado)

```
E=[roots([1 -1/3-5/3*exp(-3*T) 2/3*exp(-5*T)+exp(-3*T)-2/3*exp(-2*T)]) ; roots([1 -exp(-2*T)-exp(-3*T) exp(-5*T)])]
```

M=[M [A ; B ; C ; D ; E]];

end;

[V ; M]

T 0.05000000000000 0.10000000000000 0.50000000000000 1.00000000000000 5.00000000000000 10.00000000000000

Mapeamento Polos/Zeros

Z1 0.95122942450071 0.90483741803596 0.60653065971263 0.36787944117144 0.00673794699909 0.00004539992976
Z2 0.81873075307798 0.67032004603564 0.13533528323661 0.01831563888873 0.0000000206115 0.00000000000000
P1 0.90483741803596 0.81873075307798 0.36787944117144 0.13533528323661 0.00004539992976 0.0000000206115
P2 0.86070797642506 0.74081822068172 0.22313016014843 0.04978706836786 0.00000030590232 0.00000000000009

Forward Euler

Z1 0.95000000000000 0.90000000000000 -1.00000000000000 0 -19.00000000000000 -39.00000000000000
Z2 0.80000000000000 0.60000000000000 0.50000000000000 -3.00000000000000 -4.00000000000000 -9.00000000000000
P1 0.90000000000000 0.80000000000000 0 -2.00000000000000 -14.00000000000000 -29.00000000000000
P2 0.85000000000000 0.70000000000000 -0.50000000000000 -1.00000000000000 -9.00000000000000 -19.00000000000000

Backward Euler (INCORRETO)

Z1 0.95238095238095 0.90909090909091 0.66666666666667 0.50000000000000 0.16666666666667 0.09090909090909
Z2 0.24691358024691 0.24390243902439 0.22222222222222 0.20000000000000 0.11111111111111 0.07142857142857
P1 0.48780487804878 0.47619047619048 0.40000000000000 0.33333333333333 0.14285714285714 0.08333333333333
P2 0.32786885245902 0.32258064516129 0.28571428571429 0.25000000000000 0.12500000000000 0.07692307692308

Bilinear

Z1 0.95121951219512 0.90476190476190 0 0.33333333333333 -0.81818181818182 -0.90476190476190
Z2 0.81818181818182 0.66666666666667 0.60000000000000 -0.33333333333333 -0.42857142857143 -0.66666666666667
P1 0.90476190476190 0.81818181818182 0.33333333333333 0 -0.76470588235294 -0.87500000000000
P2 0.86046511627907 0.73913043478261 0.14285714285714 -0.20000000000000 -0.66666666666667 -0.81818181818182

Discretizacao

Z1 0.95201789030728 0.90782276370376 0.65548170606522 0.48971114916906 0.33342370093463 0.33333333745552
Z2 0.81582873706781 0.66020760409910 0.04973522751550 -0.07339936855596 -0.00008985776410 -0.0000000412203
P1 0.90483741803596 0.81873075307798 0.36787944117144 0.13533528323661 0.00004539992976 0.0000000206115
P2 0.86070797642506 0.74081822068172 0.22313016014843 0.04978706836786 0.00000030590232 0.00000000000009

OBJ.: BACKWARD EULER (RESULTADO CORRIGIDO):

Z1 0.9524 0.9091 0.6667 0.5000 0.1667 0.0909
Z2 0.8333 0.7143 0.3333 0.2000 0.0476 0.0244
P1 0.9091 0.8333 0.5000 0.3333 0.0909 0.0476
P2 0.8696 0.7692 0.4000 0.2500 0.0625 0.0323